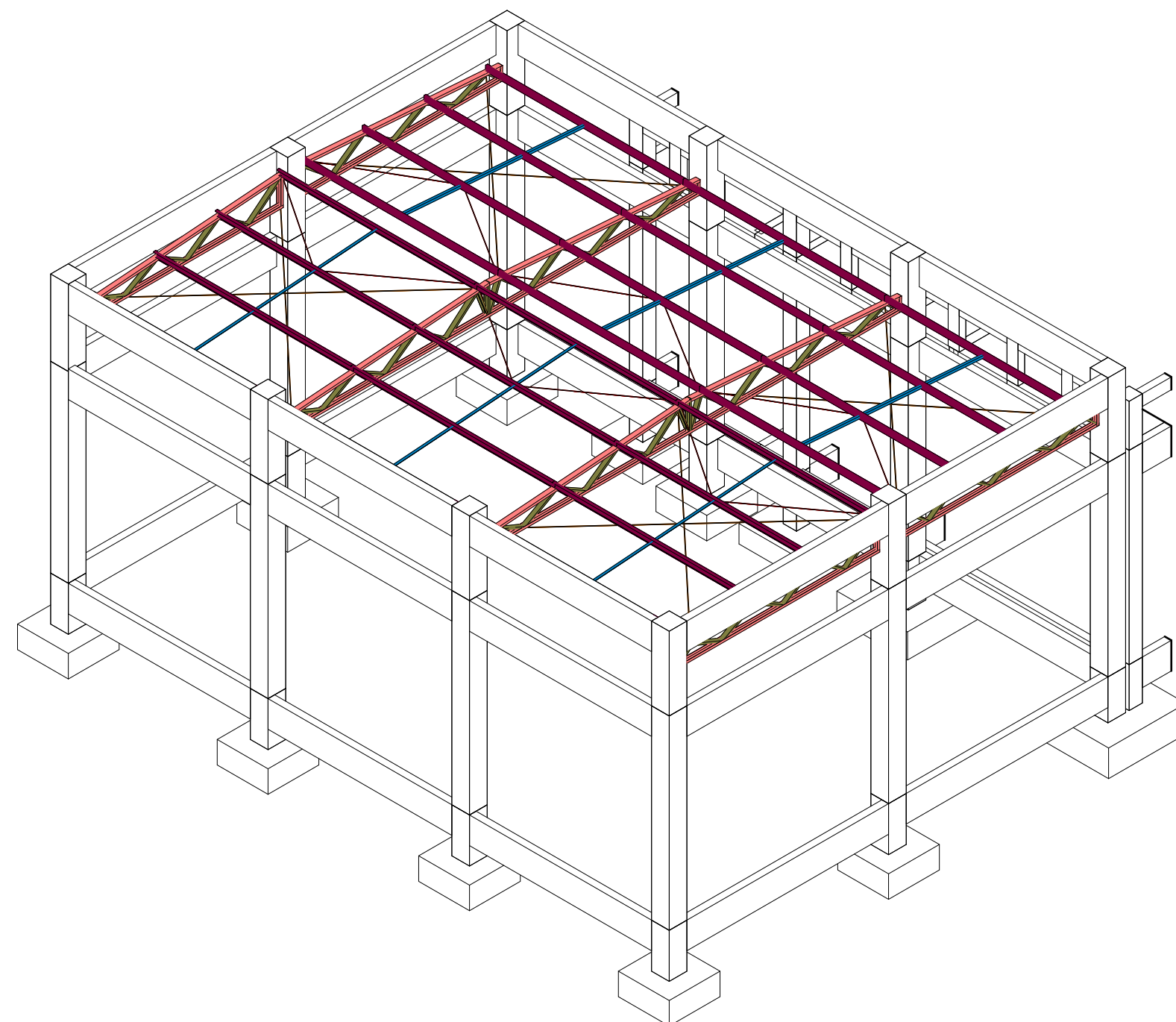
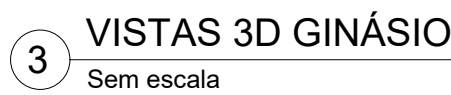
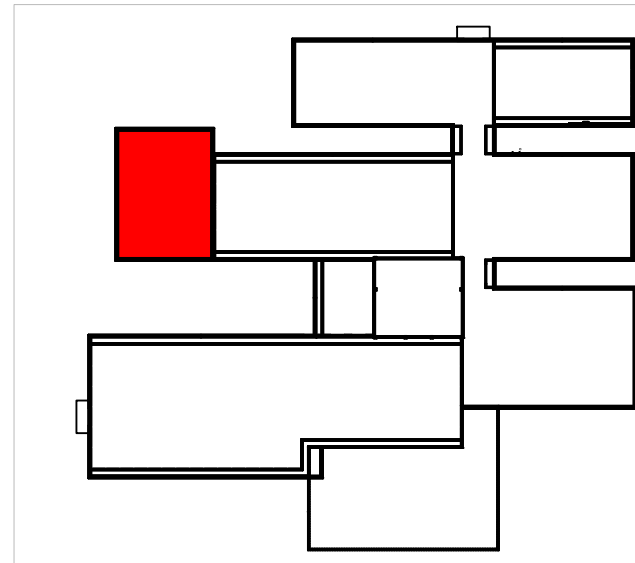




A schematic diagram of a mechanism with 6 links and 5 joints. Link 1 is the ground, represented by a fixed pivot and a sliding contact. Link 2 is a horizontal bar connected to Link 1 at a revolute joint and to Link 3 at a revolute joint. Link 3 is a vertical bar connected to Link 2 at a revolute joint and to Link 4 at a revolute joint. Link 4 is a vertical bar connected to Link 3 at a revolute joint and to Link 5 at a revolute joint. Link 5 is a vertical bar connected to Link 4 at a revolute joint and to Link 6 at a revolute joint. Link 6 is a vertical bar connected to Link 5 at a revolute joint and to Link 1 at a sliding joint. The diagram is labeled with 'S(5)' and 'L'.